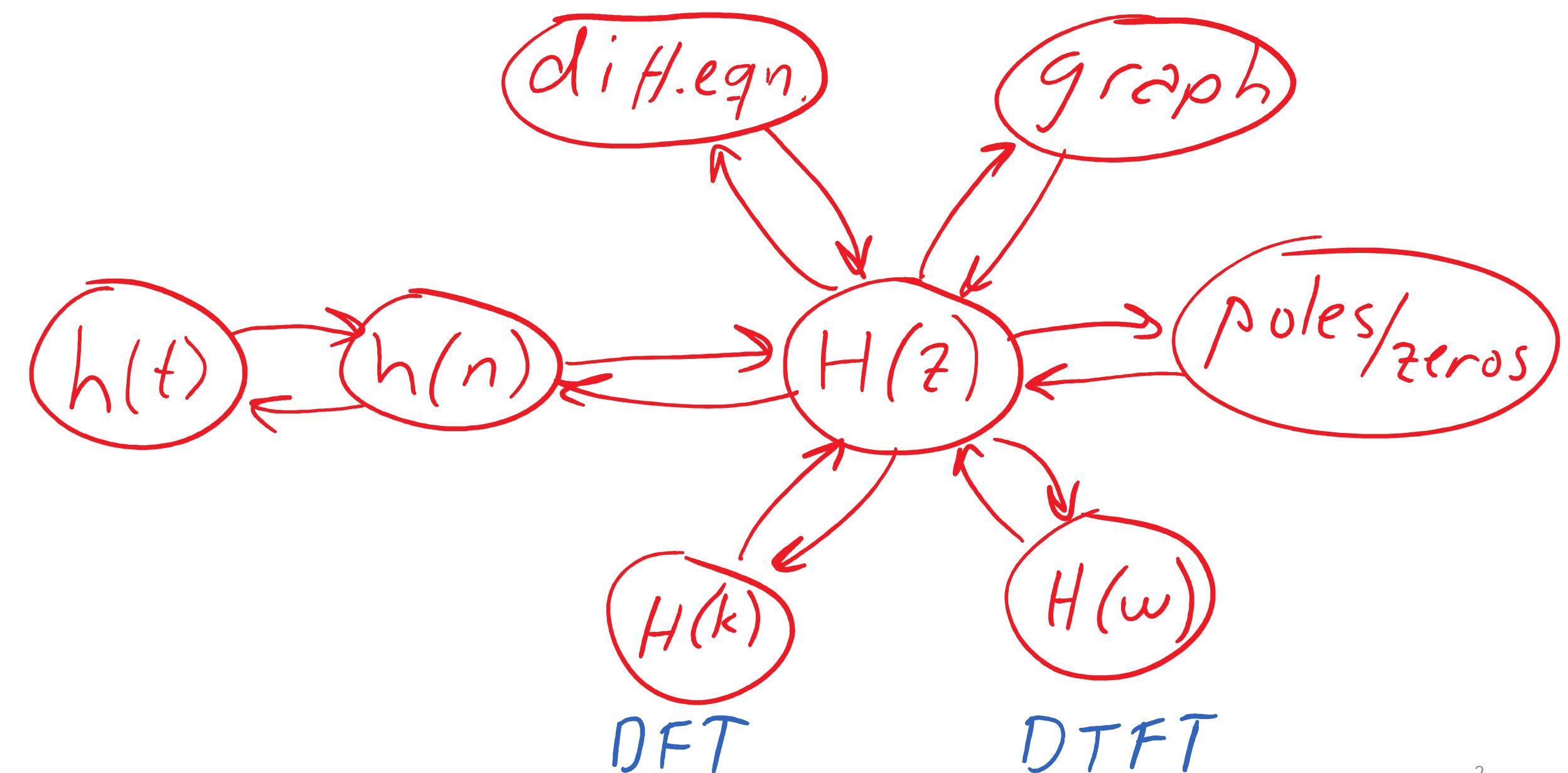


Lecture 10

Digital Signal Processing

Chapter 7

Discrete Fourier transform
DFT



We have previously defined the DTFT

The Discrete-Time Fourier Transform (DTFT)

The Fourier transform of a discrete signal:

$$X(\omega) = \sum_{n=-\infty}^{\infty} x(n)e^{-j\omega n}$$

$$x(n) = \int_{-\pi}^{\pi} X(\omega)e^{j\omega n} dt$$

$\stackrel{\omega}{\overbrace{}} = \int_0^{2\pi} X(\omega)e^{j\omega n} dt$

$\stackrel{\omega}{\overbrace{}}$

periodic with period
 $\omega = 2\pi$

We have previously defined the Z-transform

The z -transform

$$H(z) = \sum_{n=0}^{\infty} h(n)z^{-n}$$

↖ if $h(n)$ causal

$$h(n) = 0 \text{ for } n < 0$$

If $h(n)$ is causal and stable then

$$H(\omega) = H(z \mid z = e^{j\omega})$$

The Discrete Fourier Transform (DFT)

Def:

DFT

$$X_{\text{DFT}}(k) = \sum_{n=0}^{N-1} x(n)e^{-j2\pi \cdot \frac{k}{N} \cdot n} \quad \text{for } k = 0, 1, \dots, N-1$$

Inverse
DFT

$$x_{\text{DFT}}(n) = \frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k)e^{j2\pi \cdot \frac{n}{N} \cdot k} \quad \text{for } \cancel{k} = 0, 1, \dots, N-1$$

Compare the DTFT and the DFT

DTFT:

$$X(\omega) = \sum_{n=-\infty}^{\infty} x(n)e^{-j\omega n}$$

$$\omega = 2\pi \cdot \left\{ 0, \frac{1}{N}, \frac{2}{N}, \frac{3}{N}, \dots, \frac{N-1}{N} \right\}$$

If $x(n)$ is causal and has length N we get sampling of ω

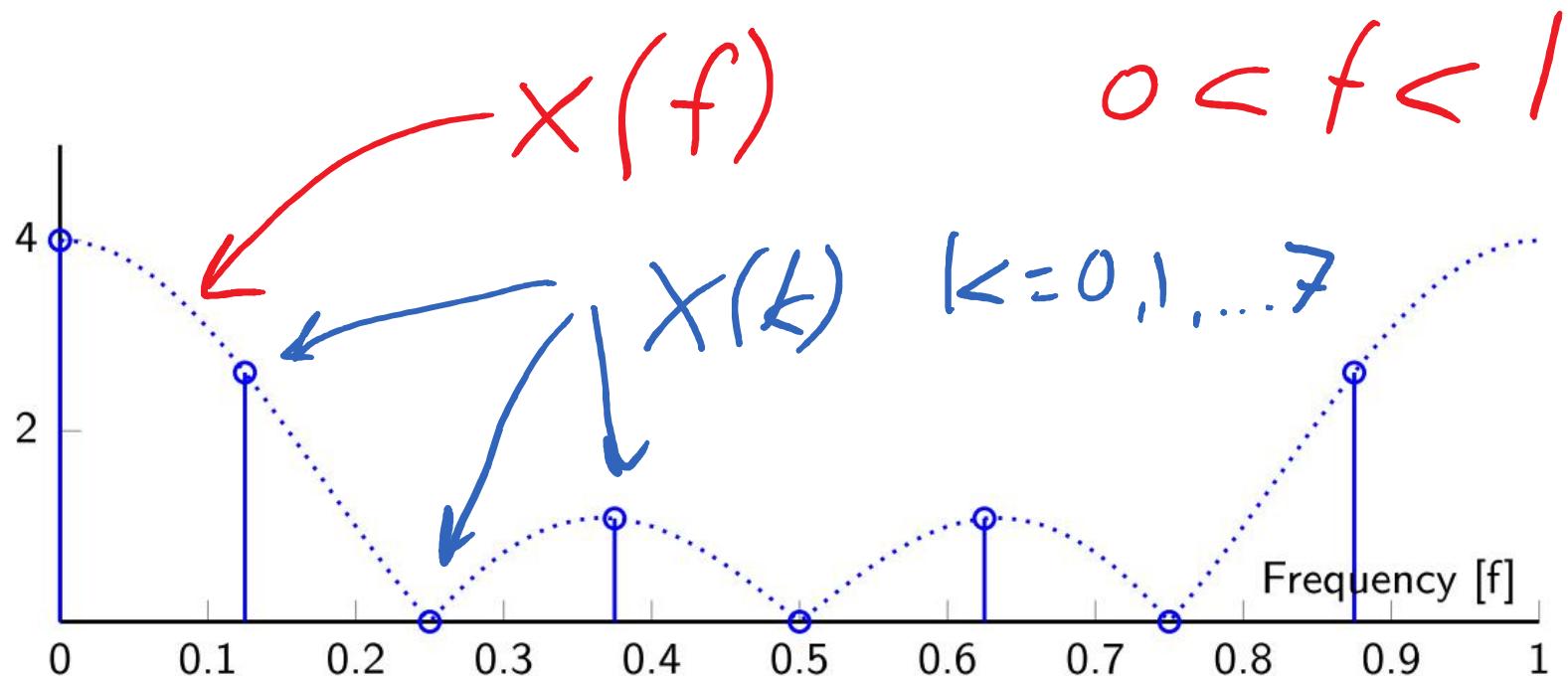
DFT:

$$X_{\text{DFT}}(k) = \sum_{n=0}^{N-1} x(n)e^{-j2\pi \cdot \frac{k}{N} \cdot n} \quad \text{for } k = 0, 1, \dots, N-1$$

$$N=8$$

Let

$$x(n) = \{ \dots 0 \underline{1} 1 1 1 0 0 0 \dots \}$$



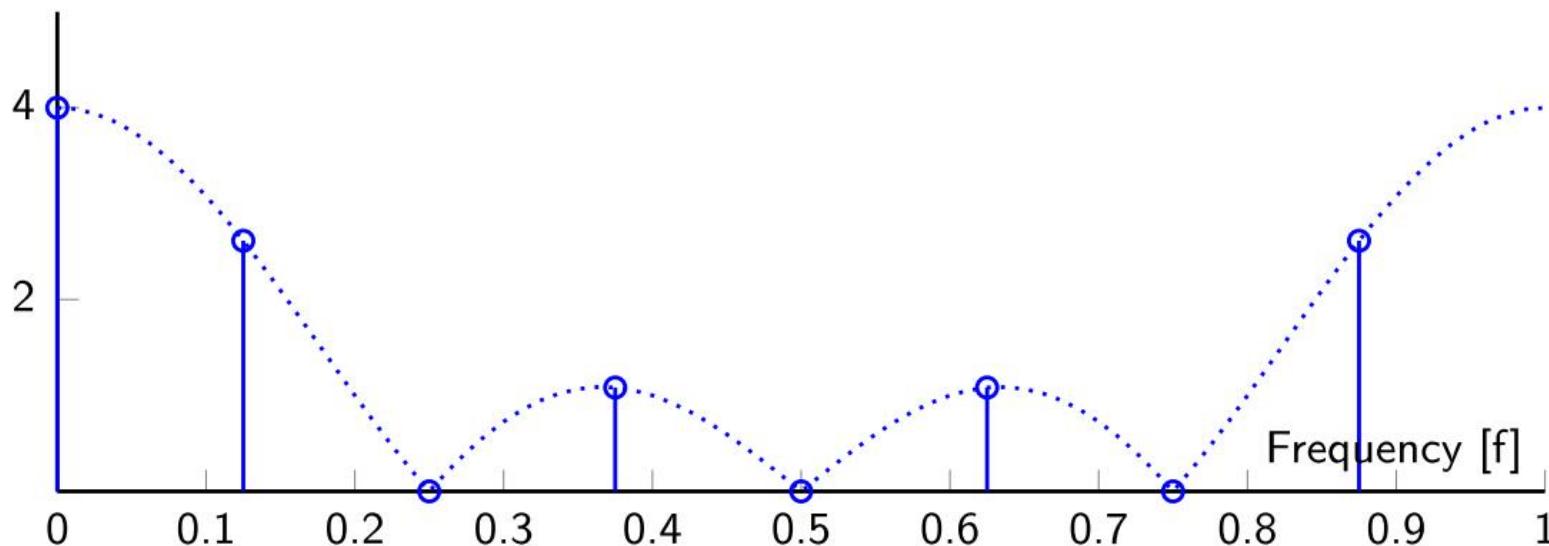
See Lecture 5 slides on page 20 for the example of calculating the Fourier transform of a discrete rectangular pulse [which gives us $X(f)$]

Conclusion

If $x(n)$ is defined only for $0 \leq n < N$ (length N) we get

$$X_{\text{DFT}}(k) = X(\omega \mid \omega = 2\pi \cdot \frac{k}{N})$$

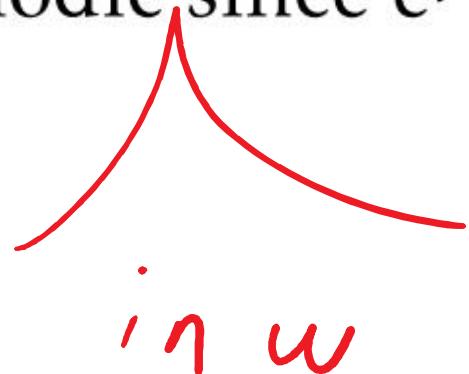
which is the same as $X(\omega)$ in N uniformly distributed frequencies.



Periodicity

The Fourier transform (DTFT)

$X(\omega)$ is periodic since $e^{j\omega n} = e^{j(\omega+2\pi)n}$.



The Discrete Fourier transform (DFT)

Both $x(n)$ and $X(k)$ are periodic with period N

since

Periodic in n

$$e^{j2\pi \cdot \frac{k}{N} \cdot (n+pN)} = e^{j2\pi \cdot \frac{k}{N} \cdot n} \cdot e^{j2\pi kp} = 1$$

Periodic in k

$$e^{j2\pi \cdot \frac{k+pN}{N} \cdot n} = e^{j2\pi \cdot \frac{k}{N} \cdot n} \cdot e^{j2\pi kp} = 1$$



Indices are calculated modulo- N

Ex | Matlab;

$$N=4$$

```
A=-5:1:6;
```

```
A=[A;mod(A,4)]
```

A =

-5	-4	-3	-2	-1	0	1	2	3	4	5	6
3	0	1	2	3	0	1	2	3	0	1	2

Roots of unity

$$\sum_{k=0}^{N-1} e^{j2\pi \cdot \frac{k}{N} \cdot (n-l)} = \begin{cases} N & \text{om } n-l = 0 + pN \\ 0 & \text{om } n-l \neq 0 + pN \end{cases}$$

$$= N \cdot \delta(n-l, \bmod N)$$

$$\equiv N \cdot \delta((n-l))_N$$

↑ notation

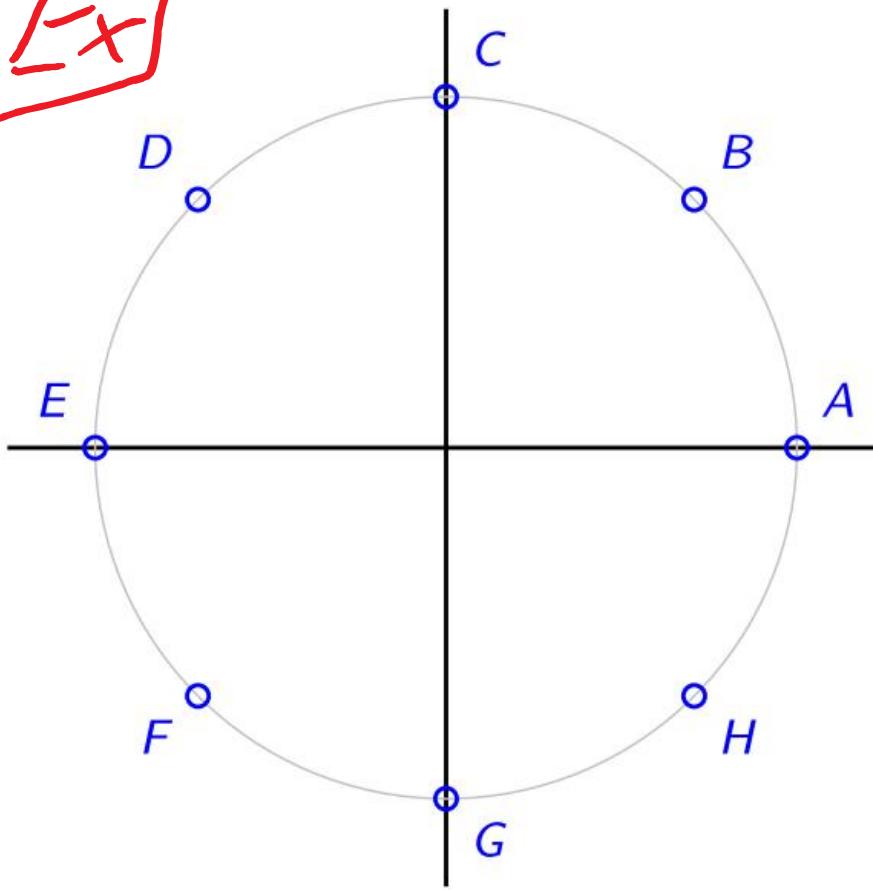
$$\sqrt[N]{1} = \sqrt[N]{e^{j2\pi k}} =$$

$$\sqrt[N]{1} \cdot e^{j2\pi \frac{k}{N}} = e^{j2\pi \frac{k}{N}}, \quad k=0,1,\dots,N-1$$

Test: $k=3$

$$\left(e^{j2\pi \frac{3}{N}}\right)^N = e^{j2\pi 3 \cdot \frac{N}{N}} = 1$$

Ex]



$$N = 8$$

$$\sum_{k=0}^{N-1} e^{j2\pi \cdot \frac{k}{N} \cdot (n-l)}$$

$$n-l$$

$$A + A + A + A + A + A + A = 8 \quad \text{for } k=0, \pm N, \pm 2N \text{ etc}$$

$$A + B + C + D + E + F + G + H = 0 \quad \text{for } k=1$$

$$A + C + E + G + A + C + E + G = 0 \quad \text{for } k=2, \text{ and so on}$$

Special properties for the DFT

Both $x(n)$ and $X(k)$ are periodic, which imposes the property that all indices are calculated modulo N .

Ex $x(n) = \{ 3 \ 4 \ \underline{1} \ 2 \ 3 \ 4 \ 1 \ \underline{2} \} \quad N = 8$ (19)

 $x(n-1) = \{ 2 \ 3 \ \underline{4} \ 1 \ 2 \ 3 \ 4 \ 1 \}$ (20)

Circular shift becomes

$$x(n - n_0, \text{ mod } N) \Rightarrow X(k) \cdot e^{-j2\pi \cdot \frac{k}{N} \cdot n_0}$$

Example of shift for the DFT: $N=4$

Ex $x(n) = \{ \underline{1} \ 2 \ 3 \ 4 \} \Rightarrow x(n-1) = \{ \underline{4} \ 1 \ 2 \ 3 \}$

Circular convolution and the DFT, length N (page 476–477)

Multiplication in the DFT-domain is circular convolution in the time domain.

$$X(k) = X_1(k) \cdot X_2(k) \Rightarrow x(n) = x_1(n) \otimes x_2(n) = \sum_{k=0}^{N-1} x_1(k) \cdot x_2(n - k, \text{ mod } N)$$

For this to be valid

Symbol for circular convolution

$x_1(n)$ and $x_2(n)$ needs to have length N

Example

Given:

$$x(n) = \{ \underline{1} \quad 2 \quad 3 \quad 4 \}$$

$$h(n) = \{ \underline{2} \quad 2 \quad 1 \quad 1 \}$$

Find:

$$y_C(n) = x(n) \otimes \underline{\textcolor{red}{h}}(n)$$

Graphical solution (with $x(n)$ repeated and $h(n)$ time reversed):

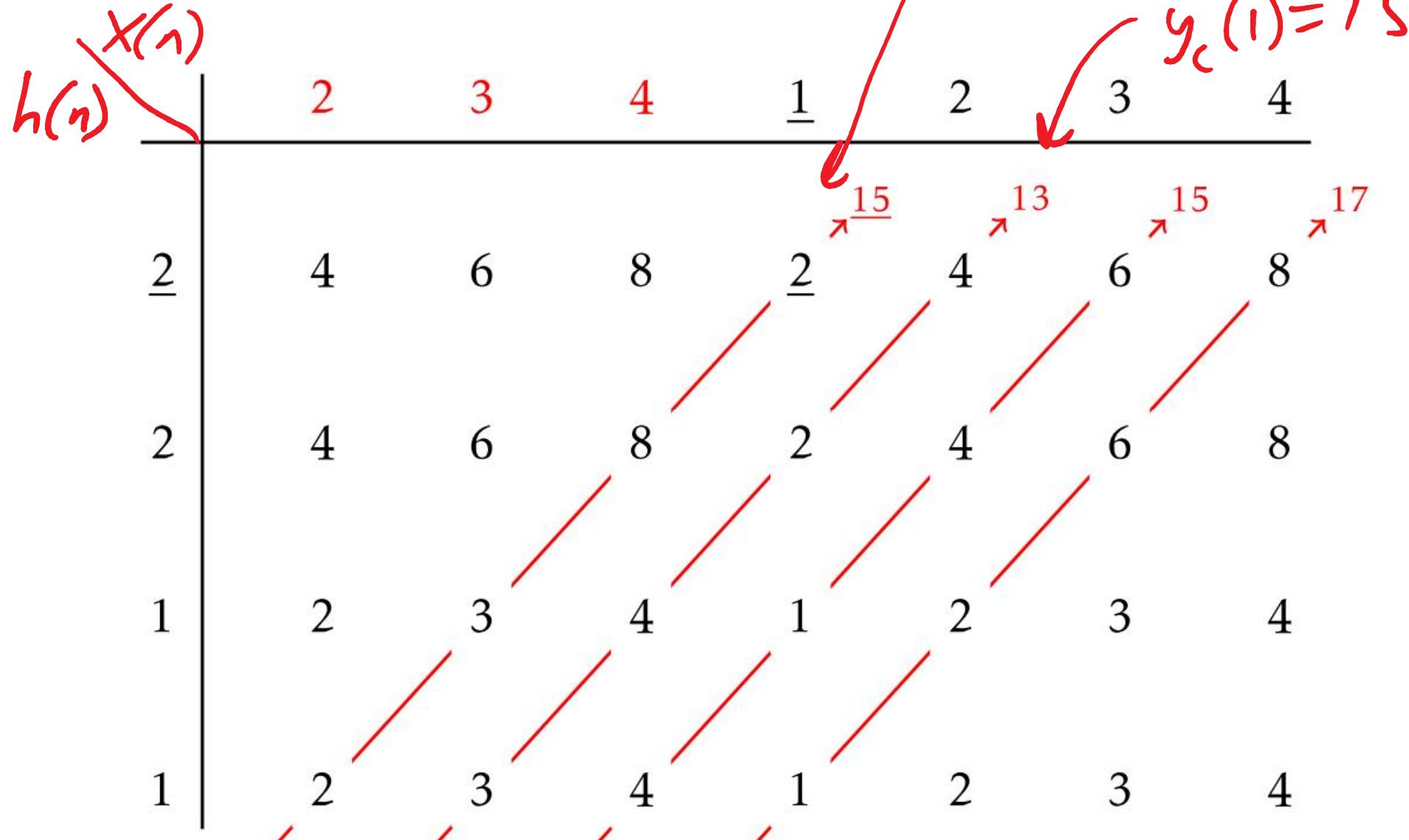
$h(k)$	1	1	2	<u>2</u>	→					
$x(k)$	2	3	4	<u>1</u>	2	3	4	1	2	3
$y_C(k)$			<u>15</u>	13	15	17				

$2 \cdot 2 + 2 \cdot 1 + 1 \cdot 4 + 1 \cdot 3 =$
 $4 + 2 + 4 + 3 = 13$

$2 \cdot 1 + 2 \cdot 4 + 3 \cdot 1 + 2 \cdot 1 =$
 $2 + 8 + 3 + 2 = 15$

Convolution

Equivalent solution with a table.



For linear convolution the length of this convolution is 7, but in circular convolution the indices wrap around modulo-4 instead.

```
>> x = [1 2 3 4];  
>> h = [2 2 1 1];  
>> yc = ifft(fft(x).*fft(h))  
yc =  
    15     13     15     17
```

We can also use the function cconv().

```
>> cconv(x,h,4)
```

ans =

```
15 13 15 17
```

equivalent if
 $\text{length}(x) = \text{length}(h) = N$

Ex $x_1(n) = \begin{bmatrix} 1 & 1 & 2 & 2 & 3 \\ \uparrow & & & & \end{bmatrix}$

$$x_2(n) = \begin{bmatrix} 1 & -1 \\ \uparrow & \end{bmatrix}$$

find $y(n) = x_1(n) \otimes_L x_2(n)$

Solution

(we had $x_1(n) = [1 \ 2 \ 2 \ 3]$
 $x_2(n) = [1 \ -1]$)

First make $x_1(n)$ and $x_2(n)$ to
N-length sequences, by truncation
or by adding zeroes.

in mod 4

$$\Rightarrow x_1(n) = [1 \ / \ 2 \ 2] \xrightarrow{\uparrow} [1 \ 2 \ 2 \ 1]$$

$$\Rightarrow x_2(n) = [1 \ -1 \ 0 \ 0] \xrightarrow{\uparrow}$$

$$\Rightarrow y(n) = X_1(n) \otimes_y X_2(n) \text{ or with a table}$$

In Matlab we can now write:

```
y=ifft(fft([1 2 2 1]).*fft([1 -1 0 0]))
```

```
y =
```

```
0 1 0 -1
```

OR

```
y=cconv([1 2 2 1],[1 -1 0 0],4)
```

```
y =
```

```
0 1 0 -1
```

$x_1 \backslash x_2$	1	2	2	1	:	1	2	2	1
1	1	2	2	1	:	1	2	2	1
-1	-1	-2	-2	-1	:	-1	-2	-2	-1
0	0	0	0	0	:	0	0	0	0
0	0	0	0	0	,	0	0	0	0

$$\Rightarrow y(n) = x_1(n) \otimes y x_2(n) \text{ or with a table}$$

In Matlab we can now write:

```
y=ifft(fft([1 2 2 1]).*fft([1 -1 0 0]))
```

y =

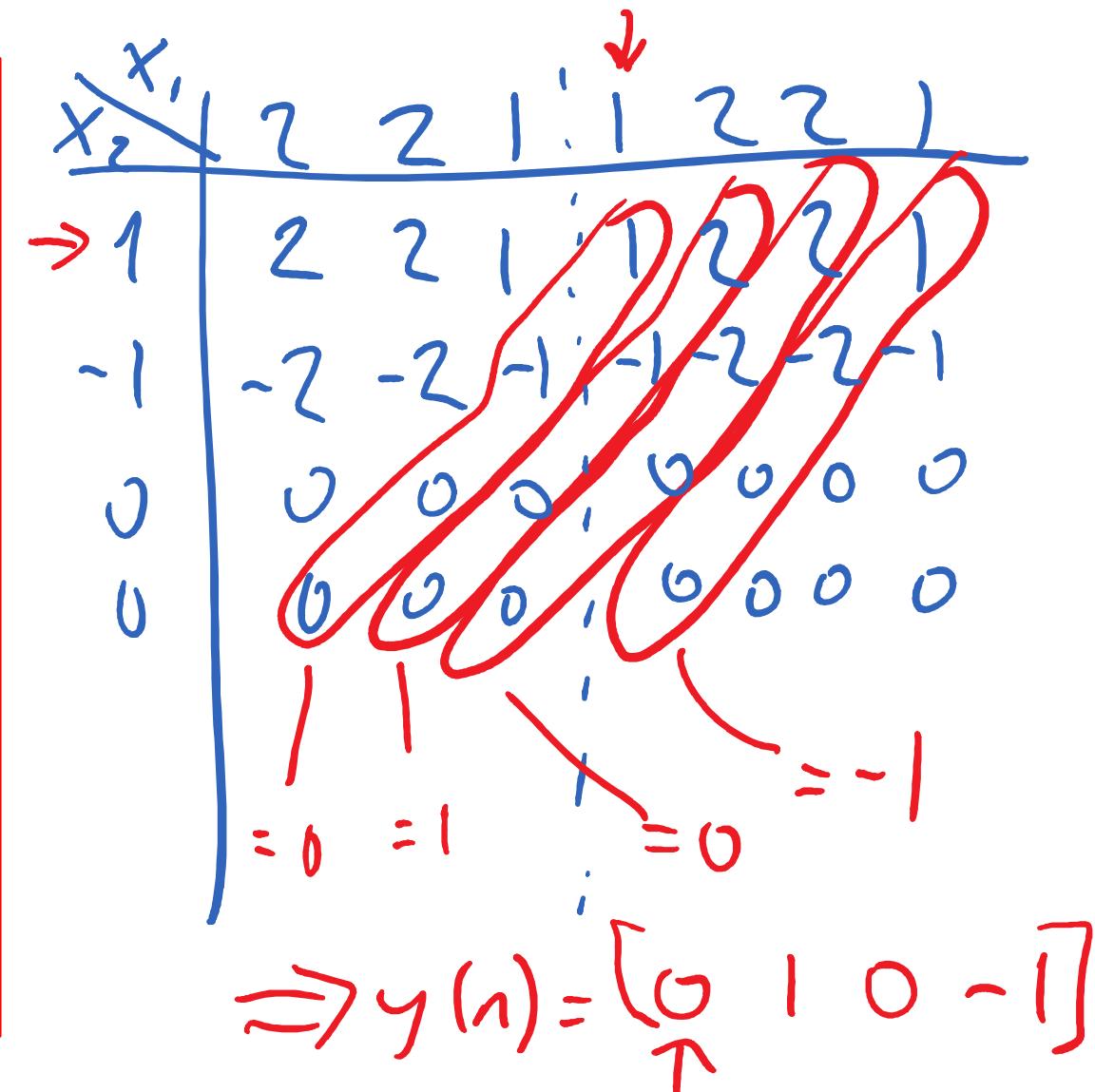
```
0 1 0 -1
```

OR

```
y=cconv([1 2 2 1],[1 -1 0 0],4)
```

y =

```
0 1 0 -1
```



Linear convolution and the DFT

The convolution between $x(n)$ and $h(n)$ yields $y(n)$ of length $4 + 4 - 1$. Choose a DFT length of $N = 8$.

$$\begin{array}{r} h(k) \quad 1 \quad 1 \quad 2 \quad \underline{2} \quad \rightarrow \\ x(k) \quad \underline{0} \quad \underline{0} \quad \underline{0} \quad \underline{1} \quad 2 \quad 3 \quad 4 \quad 0 \quad 0 \quad 0 \quad \underline{1} \quad \underline{2} \quad 3 \\ \hline y_L(k) \quad \quad \quad \underline{2} \quad 6 \quad 11 \quad 17 \quad 13 \quad 7 \quad 4 \quad 0 \end{array}$$

```
>> x = [1 2 3 4];
>> h = [2 2 1 1];
>> yl = ifft(fft(x,8).*fft(h,8)) % or we can use: cconv(x,h,8)
yl =
    2         6        11        17        13         7         4         0
```

```
>> conv([1 2 3 4],[2 2 1 1])
ans = 2   6   11  17  13  7   4
```

linear convolution

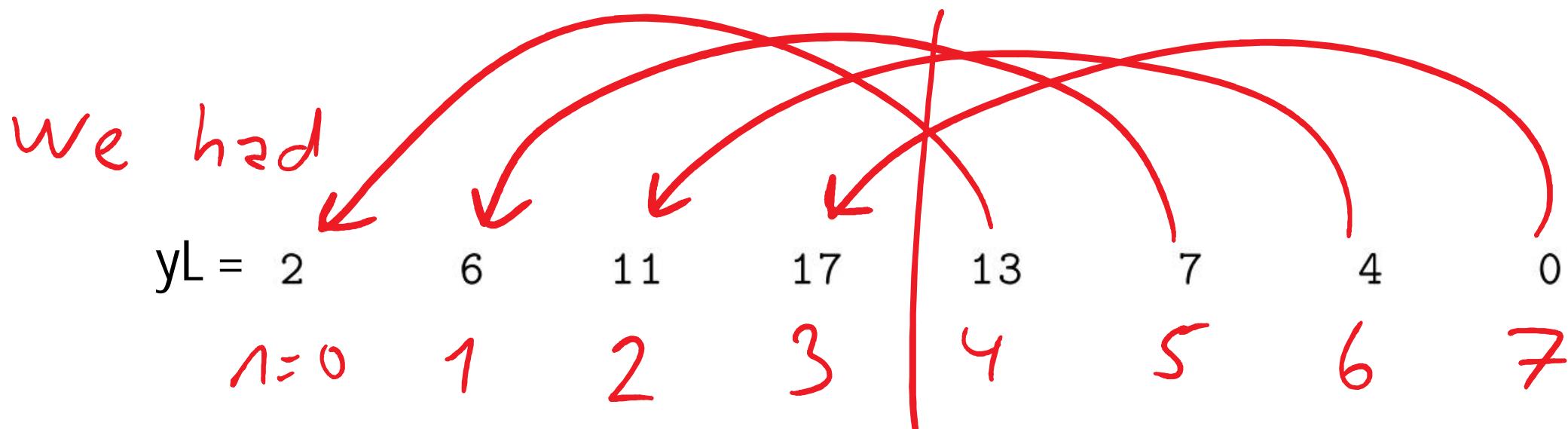
The linear convolution is closely related to the circular convolution.

Ex
cont

$$y_C(n) = \{ y_L(0) + y_L(4) \quad y_L(1) + y_L(5) \quad y_L(2) + y_L(6) \quad y_L(3) + y_L(7) \}$$

$$N=4 \\ = \{ 2+13 \quad 6+7 \quad 11+4 \quad 17+0 \}$$

$$= \{ 15 \quad 13 \quad 15 \quad 17 \}$$



Sampling the spectrum

Let

$$x(n) = a^n \cdot u(n) \Rightarrow X(\omega) = \frac{1}{1 - ae^{-j\omega}}$$

DTFT

$x(n) = ?$

IDFT



$$X(k) = \frac{1}{1 - ae^{-j2\pi \cdot \frac{k}{N}}}$$



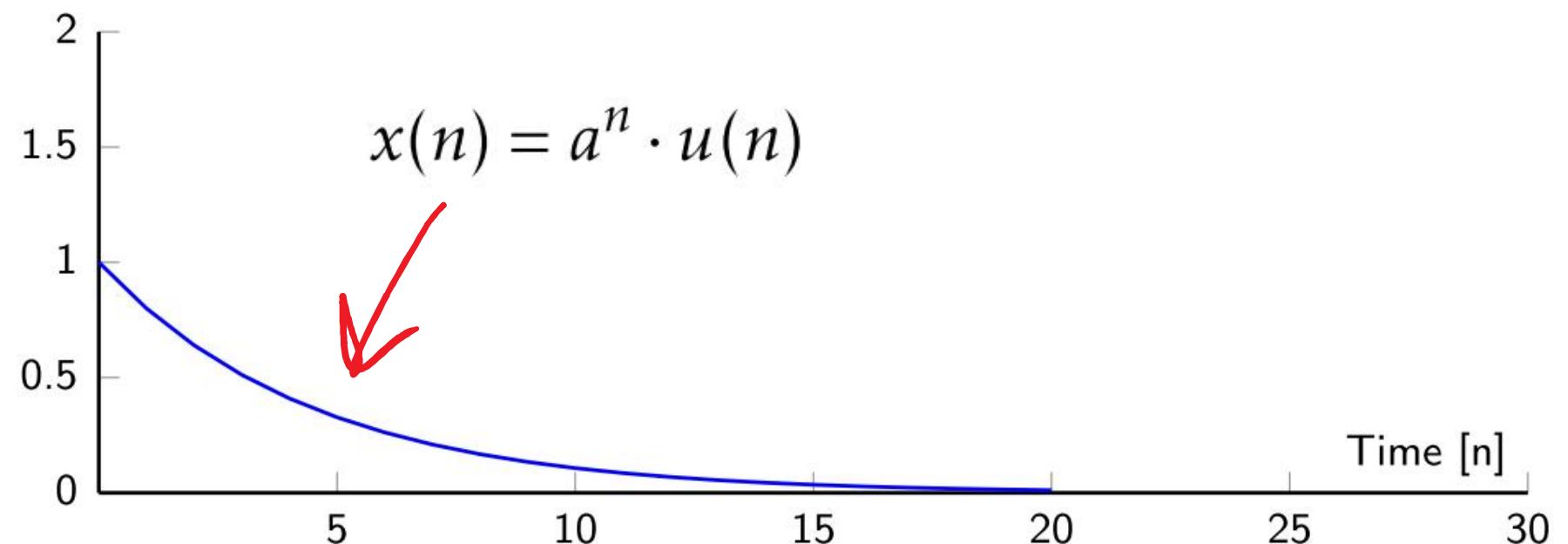
sample i.e.

$$\omega \mapsto 2\pi \frac{k}{N}$$

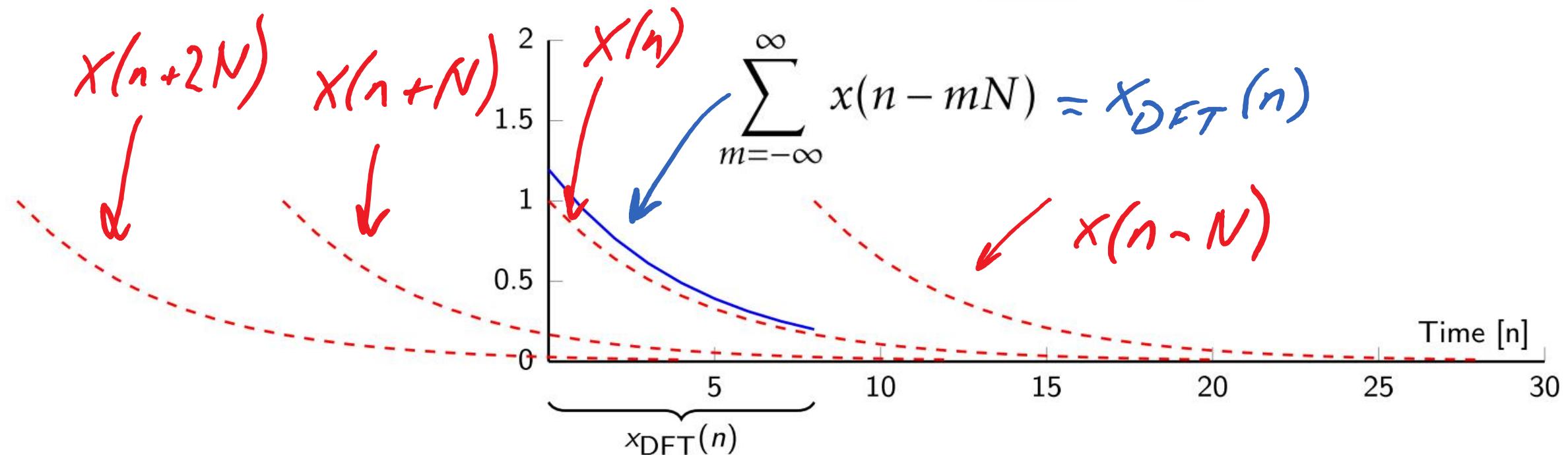
Inverse-DFT yields:

$$\begin{aligned} x_{\text{DFT}}(n) &= \frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) e^{j2\pi \cdot \frac{n}{N} \cdot k} \quad | \quad \text{IDFT} \\ &= \frac{1}{N} \cdot \sum_{k=0}^{N-1} \sum_{m=-\infty}^{\infty} x(m) e^{-j2\pi \cdot \frac{m}{N} \cdot k} \cdot e^{j2\pi \cdot \frac{n}{N} \cdot k} \quad | \quad \text{DTFT}\{x(m)\} \\ &= \frac{1}{N} \cdot \sum_{m=-\infty}^{\infty} x(m) \cdot \left[\sum_{k=0}^{N-1} e^{j2\pi \cdot \frac{n-m}{N} \cdot k} \right] \quad | \quad \text{roots of unity} \\ &= \frac{1}{N} \cdot \sum_{m=-\infty}^{\infty} x(m) \cdot N \cdot \delta(n - m \mod N) \\ &= \sum_{m=-\infty}^{\infty} x(n - mN) \end{aligned}$$

The signal $x(n)$ extends to $+\infty$.



The signal $x_{DFT}(n)$ is the sum of all shifted and repeated $x(n)$. The DFT size is $N = 8$.



Try some Matlab examples of the above effect as given in the lecture notes on page 8

A practical application

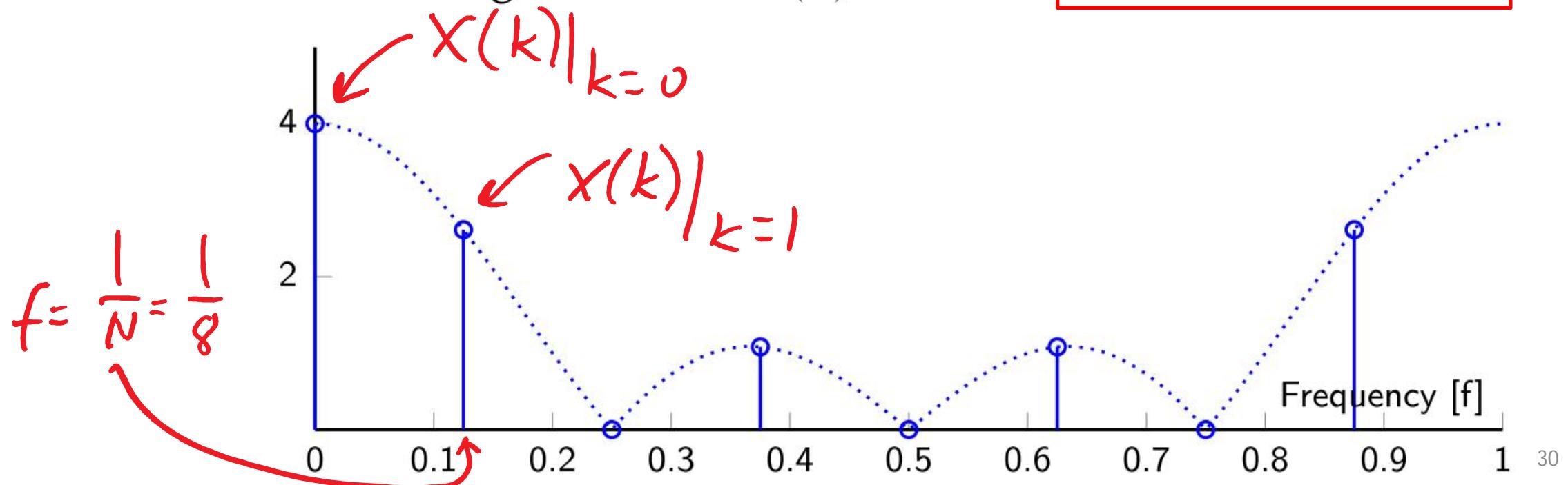
Increase the resolution in frequency by *zero padding* or *trailing zeros*.

Let

$$x(n) = \{ 1 \ 1 \ 1 \ 1 \ 0 \ 0 \ \dots \}$$

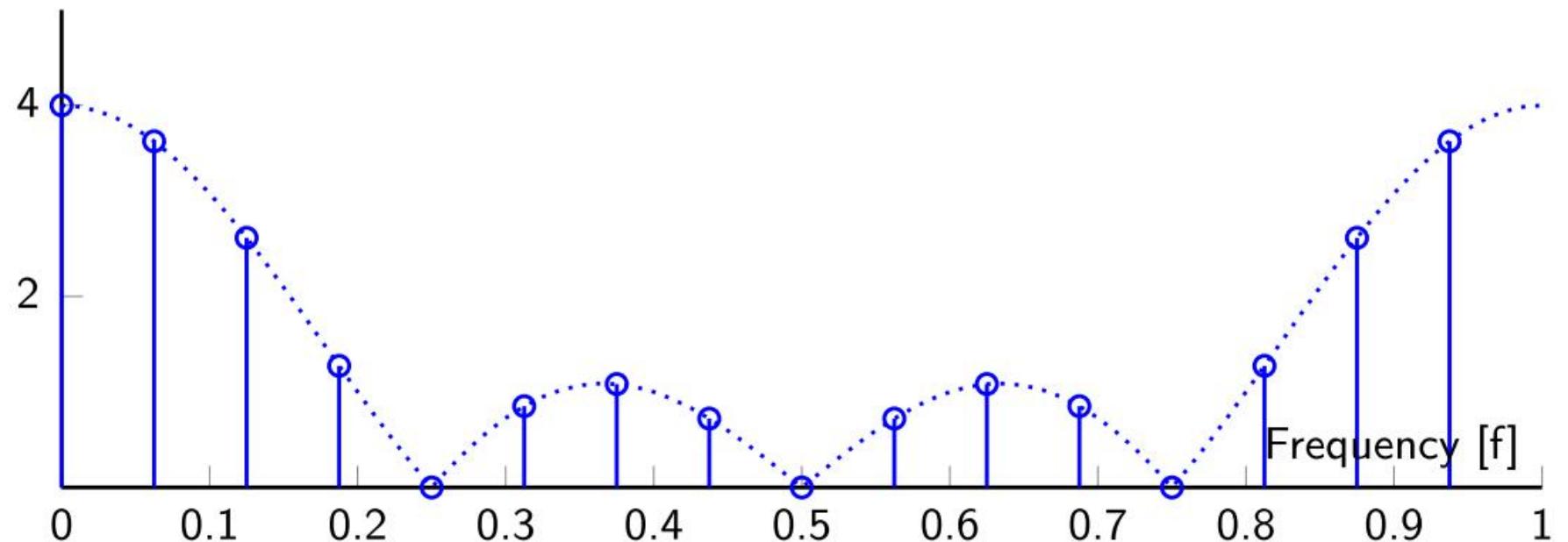
Calculate the DFT of length $N = 8$ of $x(n)$.

In matlab; `X=fft([1 1 1 1],8)`



Calculate the DFT of length $N = 16$ of $x(n)$.

In matlab; `X=fft([1 1 1 1],16)`



The DFT on matrix form (page 459–460)

Define

$$W_N = e^{-j2\pi/N} = W$$

The DFT and the IDFT becomes

$$X(k) = \sum_{n=0}^{N-1} x(n) W^{kn}$$

DFT

$$x(n) = \frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) W^{-kn}$$

IDFT

Let

$$\mathbf{x} = \begin{bmatrix} x(0) & x(1) & \cdots & x(N-1) \end{bmatrix}^T$$

vector ($N \times 1$)

and

$$\mathbf{X} = \begin{bmatrix} X(0) & X(1) & \cdots & X(N-1) \end{bmatrix}^T$$

vector ($N \times 1$)

and

$$\mathbf{D} = \begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & W & W^2 & \cdots & W^{N-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & W^{N-1} & W^{2(N-1)} & \cdots & W^{(N-1)(N-1)} \end{bmatrix}$$

matrix ($N \times N$)

Ex In Matlab:

`W=dftmtx(4)`

$$N=4$$

`W =`

```
1.0000 + 0.0000i 1.0000 + 0.0000i 1.0000 + 0.0000i 1.0000 + 0.0000i
1.0000 + 0.0000i 0.0000 - 1.0000i -1.0000 + 0.0000i 0.0000 + 1.0000i
1.0000 + 0.0000i -1.0000 + 0.0000i 1.0000 + 0.0000i -1.0000 + 0.0000i
1.0000 + 0.0000i 0.0000 + 1.0000i -1.0000 + 0.0000i 0.0000 - 1.0000i
```

~~now~~
We can not describe the DFT and the IDFT as

$$\mathbf{X} = \mathbf{D}\mathbf{x}$$

DFT

and

$$\mathbf{x} = \mathbf{D}^{-1}\mathbf{X}$$

IDFT

Discrete
Prove the Fourier-
transf!

$$\mathbf{X} = \mathbf{D}' \cdot \mathbf{X} = \underbrace{\mathbf{D}' \cdot \mathbf{D}}_{= \mathbf{I}} \cdot \mathbf{x} = \mathbf{x}$$